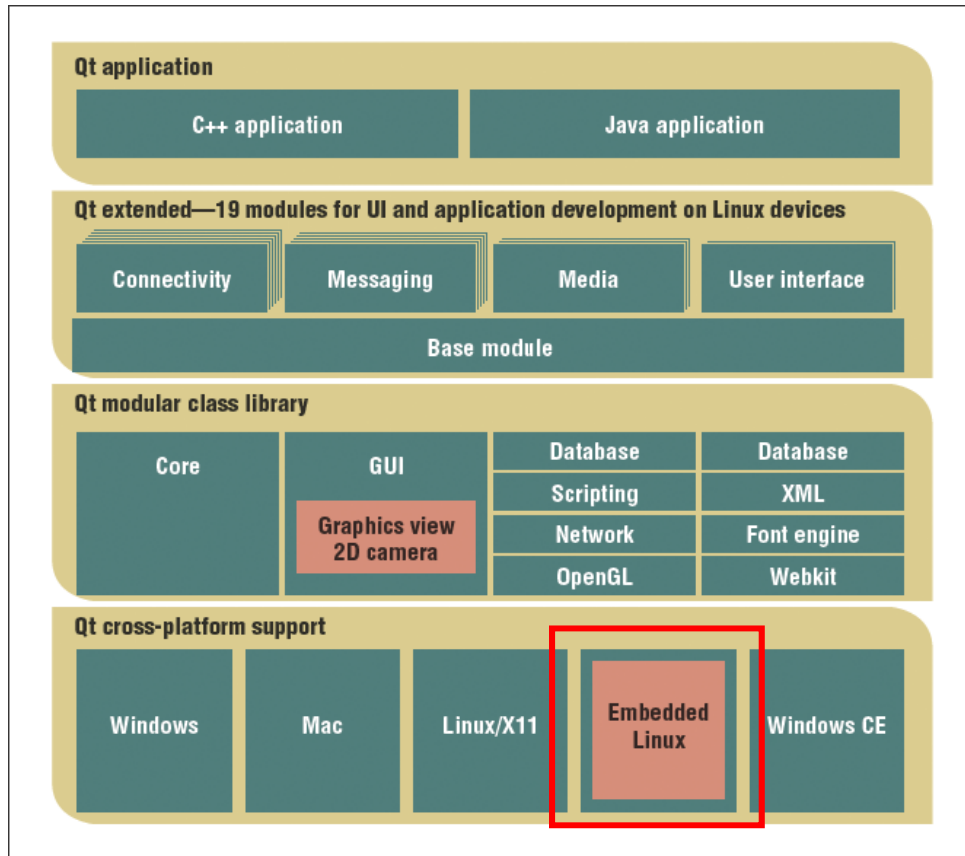


## 1. HMI Linux – QT Version

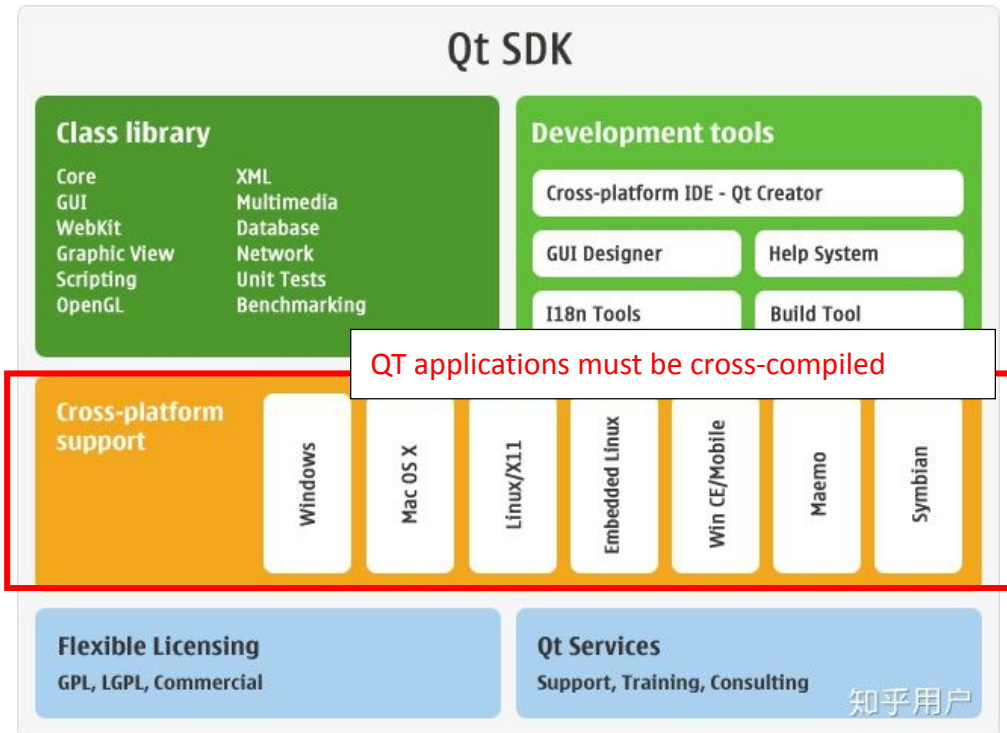
### QT Architecture Diagram

QT supports multiple platforms, so it only provides minimal library support. The HMI LINUX is an embedded Linux category.



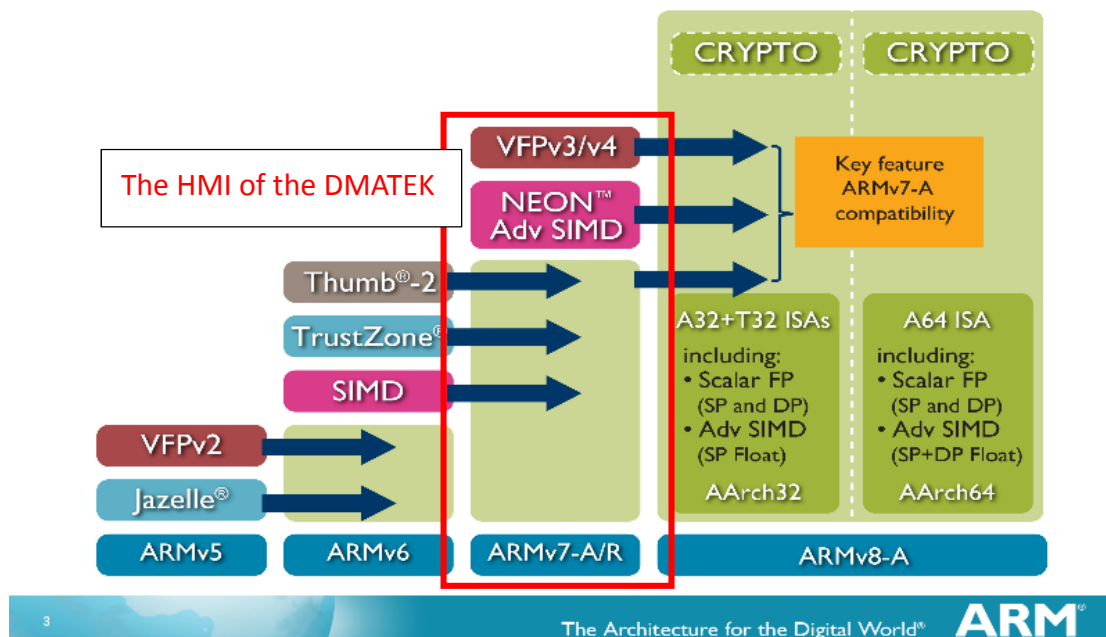
## Development Notice

- (1) Applications compiled directly from the QT IDE development environment cannot be executed directly on HMI LINUX. Applications on the ARM platform must be cross-compiled before they be executed.

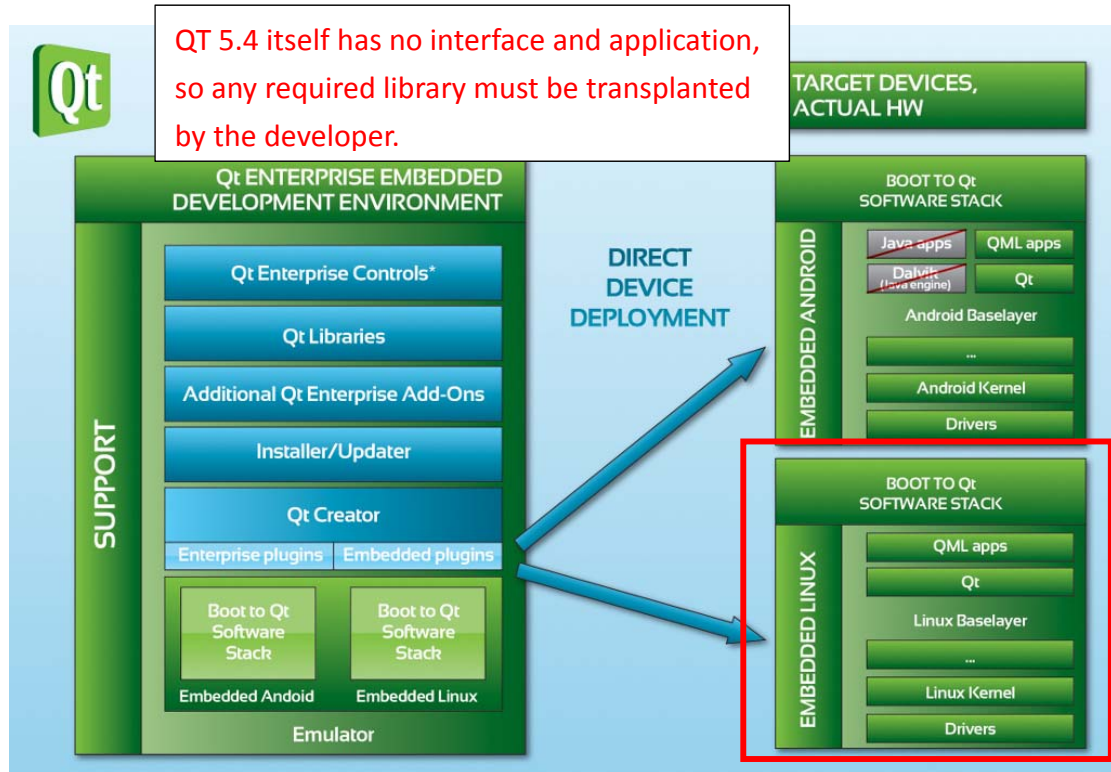


- (2) According to the type of ARM, the supported functions are also different. The HMI of the DMATEK uses ArmV7, and the ARMv7 supports 32-bit space and 32-bit operations. Support for 64-bit computing is only available on Amv8 and above.

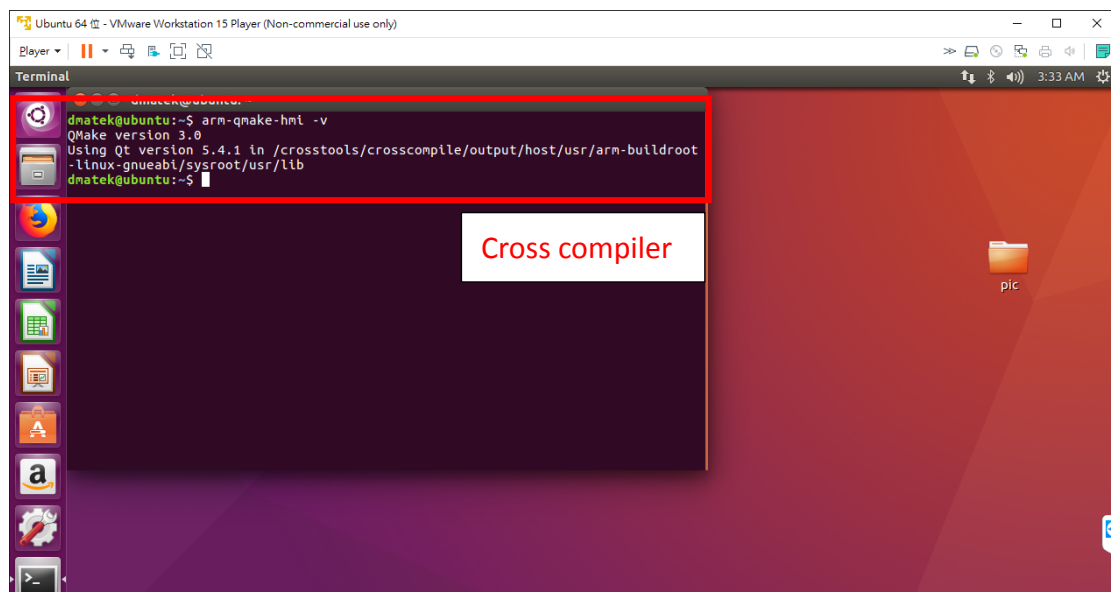
## ARMv7-A => ARMv8-A development



(3) The HMI of the DMATEK currently offers a QT 5.4 environment with minimal library support. Any required development libraries such as nodejs, php, etc., developers must cross-compile to transplant



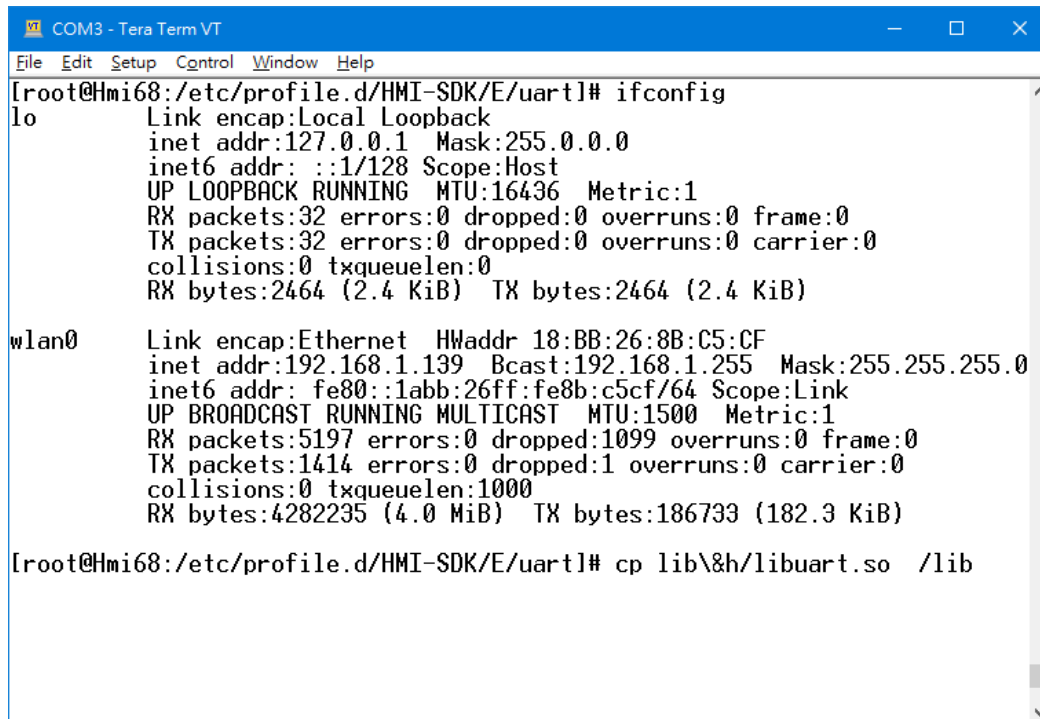
- (4) The development environment provided by the HMI of the DMATEK is as follows
- Ubuntu.iso with development tools such as cross compilers
  - Development documents
  - Cross compiler



(5) The HMI of the DMATEK only provides a simple demo interface and SDK .

### Command interface

a. Command interface - general linux command

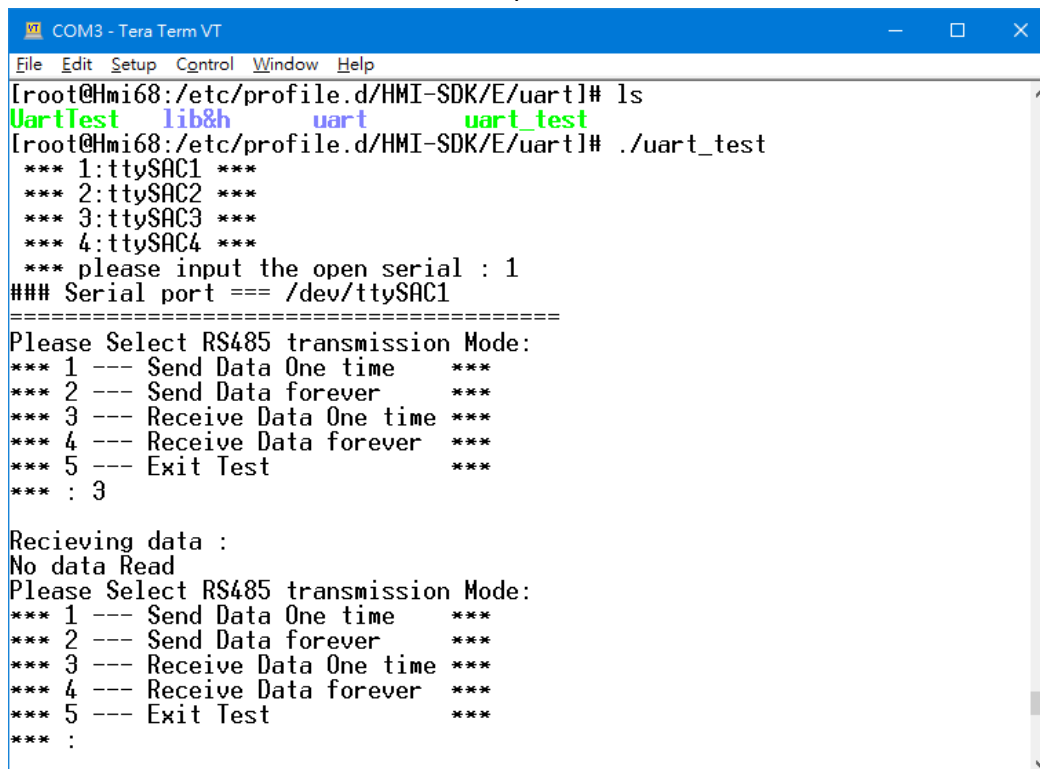


```
COM3 - Tera Term VT
File Edit Setup Control Window Help
[root@Hmi68:/etc/profile.d/HMI-SDK/E/uart1# ifconfig
lo          Link encap:Local Loopback
           inet addr:127.0.0.1  Mask:255.0.0.0
           inet6 addr: ::1/128 Scope:Host
           UP LOOPBACK RUNNING  MTU:16436  Metric:1
           RX packets:32 errors:0 dropped:0 overruns:0 frame:0
           TX packets:32 errors:0 dropped:0 overruns:0 carrier:0
           collisions:0 txqueuelen:0
           RX bytes:2464 (2.4 KiB)  TX bytes:2464 (2.4 KiB)

wlan0      Link encap:Ethernet  HWaddr 18:BB:26:8B:C5:CF
           inet addr:192.168.1.139 Bcast:192.168.1.255 Mask:255.255.255.0
           inet6 addr: fe80::1abb:26ff:fe8b:c5cf/64 Scope:Link
           UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
           RX packets:5197 errors:0 dropped:1099 overruns:0 frame:0
           TX packets:1414 errors:0 dropped:1 overruns:0 carrier:0
           collisions:0 txqueuelen:1000
           RX bytes:4282235 (4.0 MiB)  TX bytes:186733 (182.3 KiB)

[root@Hmi68:/etc/profile.d/HMI-SDK/E/uart1# cp lib\&h/libuart.so /lib
```

b. Command interface - SDK example, UART demo



```
COM3 - Tera Term VT
File Edit Setup Control Window Help
[root@Hmi68:/etc/profile.d/HMI-SDK/E/uart1# ls
UartTest lib&h uart uart_test
[root@Hmi68:/etc/profile.d/HMI-SDK/E/uart1# ./uart_test
*** 1:ttySAC1 ***
*** 2:ttySAC2 ***
*** 3:ttySAC3 ***
*** 4:ttySAC4 ***
*** please input the open serial : 1
### Serial port === /dev/ttySAC1
=====
Please Select RS485 transmission Mode:
*** 1 --- Send Data One time ***
*** 2 --- Send Data forever ***
*** 3 --- Receive Data One time ***
*** 4 --- Receive Data forever ***
*** 5 --- Exit Test ***
*** : 3

Receiving data :
No data Read
Please Select RS485 transmission Mode:
*** 1 --- Send Data One time ***
*** 2 --- Send Data forever ***
*** 3 --- Receive Data One time ***
*** 4 --- Receive Data forever ***
*** 5 --- Exit Test ***
*** :
```

## Graphical interface

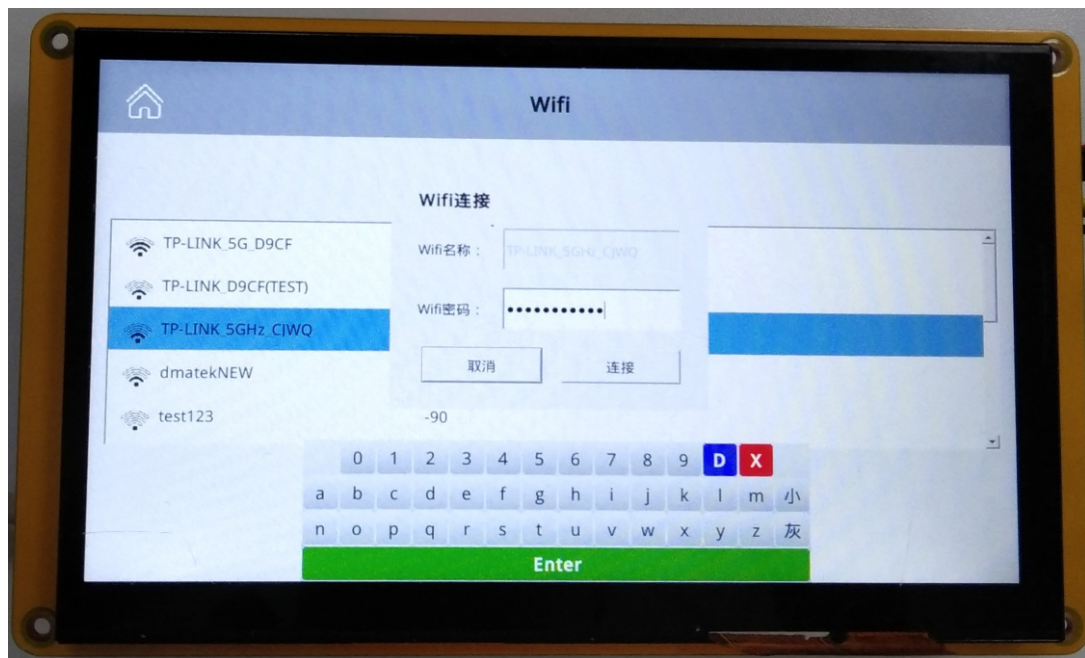
✧The test application on the interface is as follows

Application	Application function
Uart	<ol style="list-style-type: none"><li>1. RS232/RS485-serial port on/off</li><li>2. COM1 / COM2 / COM3 - 3-channel serial port selection</li><li>3. 9600/19200/57600/115200 - 4 baud rate selection</li><li>4. Data transmission and reception</li></ol>
GPIO	<ol style="list-style-type: none"><li>1. 8-channel input detection</li><li>2. 8-channel output potential setting and reading</li></ol>
Buzzer	<ol style="list-style-type: none"><li>1. Buzzer function test - on/off</li></ol>
Backlight	<ol style="list-style-type: none"><li>1. Backlight function test - The value is adjustable from 10 to 255. The bigger the number, the brighter it is.</li></ol>
WIFI	<ol style="list-style-type: none"><li>1. WIFI function test - open / search / connect / close</li></ol>
LCD	<ol style="list-style-type: none"><li>1. LCD colors - click on the screen to change color</li></ol>
Touch	<ol style="list-style-type: none"><li>1. Four-point touch point track display</li></ol>
Ethernet	<ol style="list-style-type: none"><li>1. DHCP function test</li><li>2. Static IP function test</li></ol>
Browser	<ol style="list-style-type: none"><li>1. Internet web page test - test network connection</li></ol>
Language	<ol style="list-style-type: none"><li>1. Three language changes - Traditional/Simplified/English</li></ol>

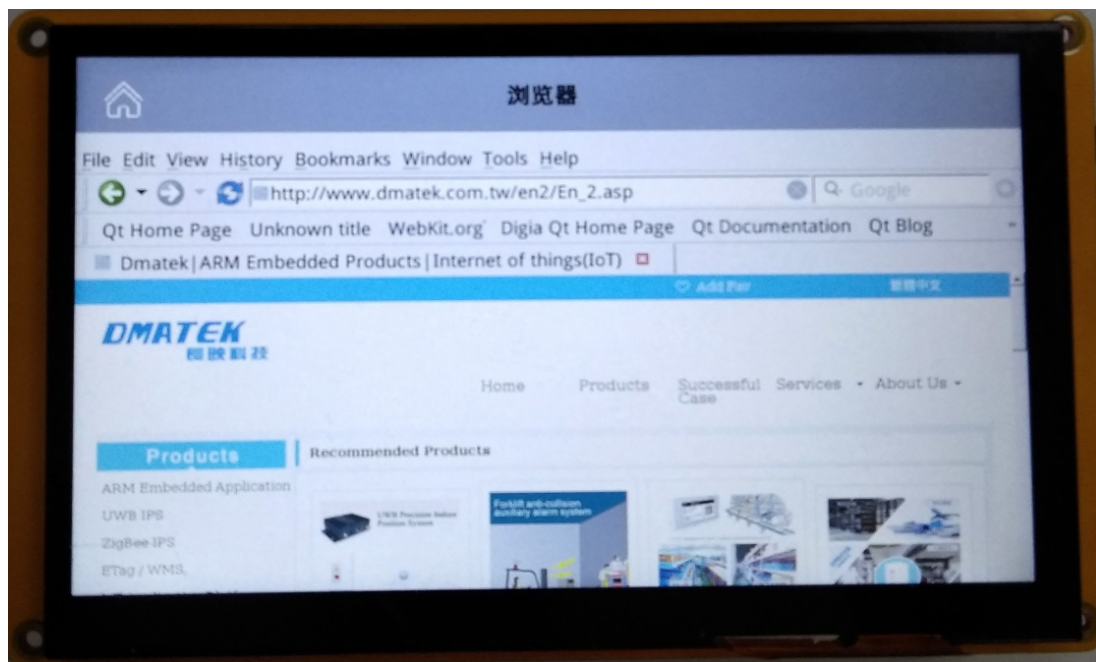
a. User interface - OT test application



b. User interface - WIFI connection test picture



c. User interface - QT browser test picture



(6) Hardware development

- a. If the application involves controlling the underlying hardware, such as UART, reboot, and so on. Developers need to call the SO file provided by DMATEK (providing a function interface to control the hardware)
- b. If the developer wants to add equipment such as sensors. Unless DMATEK already provides control methods (such as uart, gpio, etc. already provided in the SDK), please contact DMATEK when ordering.
- c. GPIO is a fixed 8-channel output and 8-channel input. For other GPIO function requirements, please submit it at the time of ordering. GPIO output voltage is 3.3V
- d. RS232 and RS485 functions are only potential conversion after UART output. Currently, HMI does not provide upper layer communication protocol such as Modbus.

**SDK Content**

Item	SDK	Demo Function
Backlight	libbacklight.so	<ol style="list-style-type: none"><li>1. Backlight brightness adjustment</li><li>2. Command interface example</li><li>3. QT interface example</li></ol>
Buzzer	libbuzzer.so	<ol style="list-style-type: none"><li>1. Turn on the buzzer</li><li>2. Turn off the buzzer</li><li>3. Get the buzzer status</li><li>4. Command interface example</li><li>5. QT interface example</li></ol>
front	Nono	<ol style="list-style-type: none"><li>1. Install display font</li><li>2. Call display font</li><li>3. QT interface display example</li></ol>
GPIO	libgpio.so (Single GPIO control)	<ol style="list-style-type: none"><li>1. Set a single output to high potential</li><li>2. Set a single output to low potential</li><li>3. Read the output potential state</li><li>4. Detecting the input potential state</li><li>5. Command interface example</li><li>6. QT interface example</li></ol>
	libgpio.so (8-channel control)	<ol style="list-style-type: none"><li>1. This feature requires updating image</li><li>2. Simultaneously set the 8-channel output potential</li><li>3. Simultaneously read the 8-channel input</li></ol>

		<p>potential state</p> <ol style="list-style-type: none"> <li>4. Command interface example</li> </ol>
UART	libuart.so	<ol style="list-style-type: none"> <li>1. Turn on the UART and receive messages</li> <li>2. Send hex message</li> <li>3. Send string message</li> <li>4. Command interface example</li> <li>5. QT interface example</li> </ol>
USB Update	Nono	<ol style="list-style-type: none"> <li>1. Update installed apps with USB</li> <li>2. QT interface update apps example</li> </ol>
WIFI	libWifiLib.so libWifiLib.so.1 libWifiLib.so.1.0 libWifiLib.so.1.0.0	<ol style="list-style-type: none"> <li>1. Turn on WIFI function</li> <li>2. Search WIFI</li> <li>3. Get WIFI strength, SSID and other information</li> <li>4. Connect to WIFI</li> <li>5. Turn off WIFI function</li> <li>6. QT interface example</li> </ol>